




Compiler Optimization Modulo Axioms

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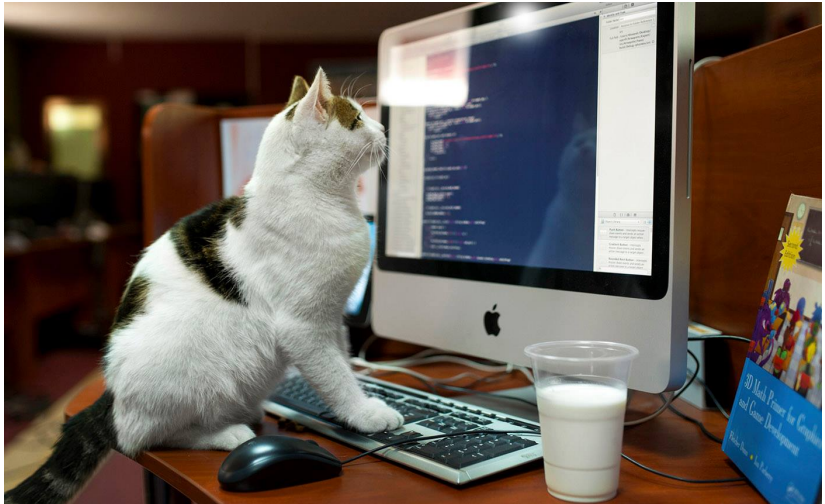
with the Bergen Language Design Laboratory (BLDL)

Department of Informatics
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2002.
-  David Lacey and Oege De Moor.
Imperative program transformation by rewriting.
In *Compiler Construction*, pages 52–68. Springer, 2001.
-  Xiaolong Tang and Jaakko Järvi.
Concept-based optimization.
Proceedings of the 2007 Symposium on Library-Centric Software Design - LCSD '07, pages 97–108, 2007.

- Optimization often uses hardcoded information.
- Programmers abstraction is not visible to the compiler.
- Information used for verification can often be used for optimization.
- Several techniques (such as SSA form) apply to both.

- Optimization often uses hardcoded information.
- Programmers abstraction is not visible to the compiler.
- Information used for verification can often be used for optimization.
- Several techniques (such as SSA form) apply to both.
- Goal: Incorporating verification techniques into compiler optimization.
- Poses an additional challenge: Only exhaustive checks are useful.



```
Assert  $0 \leq i < \text{array.length}$ ;  
b := array[i];
```

Example

```
deltax := x1 - x0;
deltay := y1 - y0;
error := deltax / 2;
y := y0;
for x from x0 to x1 do
  | safeplot(x,y) ; // performs a bounds check
  | if error < 0 then
  |   | y := y + 1;
  |   | error := error + deltax;
  | end
end
```

Example

```
deltax := x1 - x0;
deltay := y1 - y0;
Assert((deltax > 0) and (deltay > 0) and deltax ≤ deltax);
error := deltax / 2;
y := y0;
for x from x0 to x1 do
  | Invariant(x0 ≤ x ≤ x1);
  | Invariant(y0 ≤ x ≤ y1);
  | Invariant(...);
  safeplot(x,y) ; // performs a bounds check
  if error < 0 then
    | y := y + 1;
    | error := error + deltax;
  end
end
```


Example

```
deltax := x1 - x0;
deltay := y1 - y0;
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error := deltax / 2;
y := y0;
for x from x0 to x1 do
  | Invariant(x0 ≤ x ≤ x1);
  | Invariant(y0 ≤ x ≤ y1);
  | Invariant(...);
  unsafeplot(x,y) ;
  if error < 0 then
    | y := y + 1;
    | error := error + deltax;
  end
end
```

- Liveness.
- Common subexpression elimination.
- Rewriting rules of the form $\forall \mathbf{a}. P(\mathbf{a}) \Rightarrow E_1(\mathbf{a}) \rightarrow E_2(\mathbf{a})$.
eg. $\forall x_1, x_2. x_2 = 0 \Rightarrow x_1 + x_2 \rightarrow x_1$

$\forall \mathbf{a}. P(\mathbf{a}) \Rightarrow E_1(\mathbf{a}) \rightarrow E_2(\mathbf{a})$.

Use unification to determine whether the rewriting rule is applicable. Use theorem prover to determine whether the guard holds.

Not as strong as $(\forall \mathbf{x}. E_1(\mathbf{x}) = E_2(\mathbf{x})) \models \exists \mathbf{z}. E_2(\mathbf{z}) = Q(\mathbf{y})$.

- Do away with data dependency with SSA form.
 - Only one assignment for each variable.
 - Data dependencies hidden behind phi functions.
- Do away with control dependency with post domination front.
- Does not capture (all) interdependencies between data and control.

Example

```
deltax := x1 - x0;
deltay := y1 - y0;
Assert((deltax > 0) and (deltay > 0) and deltax ≤ deltax);
error1 := deltax / 2;
y1 := y0;
for x from x0 to x1 do
  | y3 := φ(y1,y2);
  | error3 := φ(error1,error2);
  | safeplot(x,y3) ; // performs a bounds check
  | if error3 < 0 then
    | | y2 := y3 + 1;
    | | error2 := error3 + deltax;
  | end
end
```

- Experimental evaluation.
- Experiment with Candidate annotation generation.